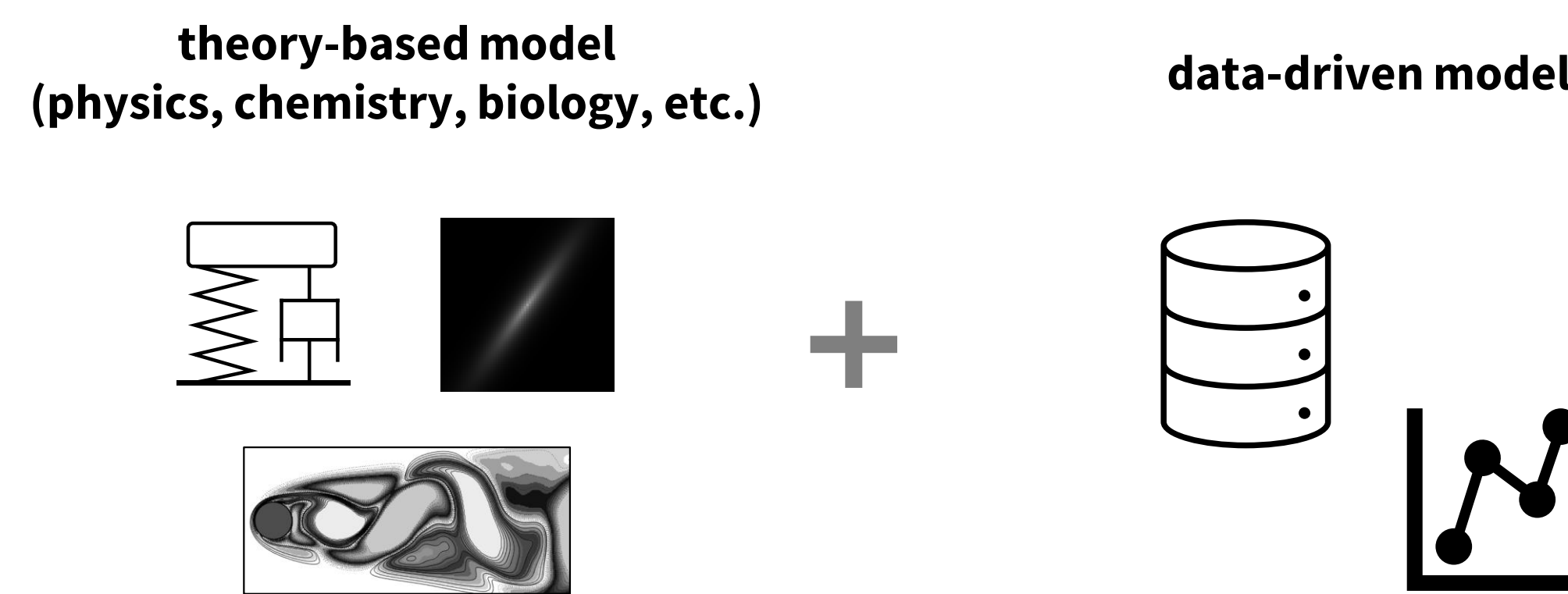


Physics-Integrated Variational Autoencoders for Robust and Interpretable Generative Modeling

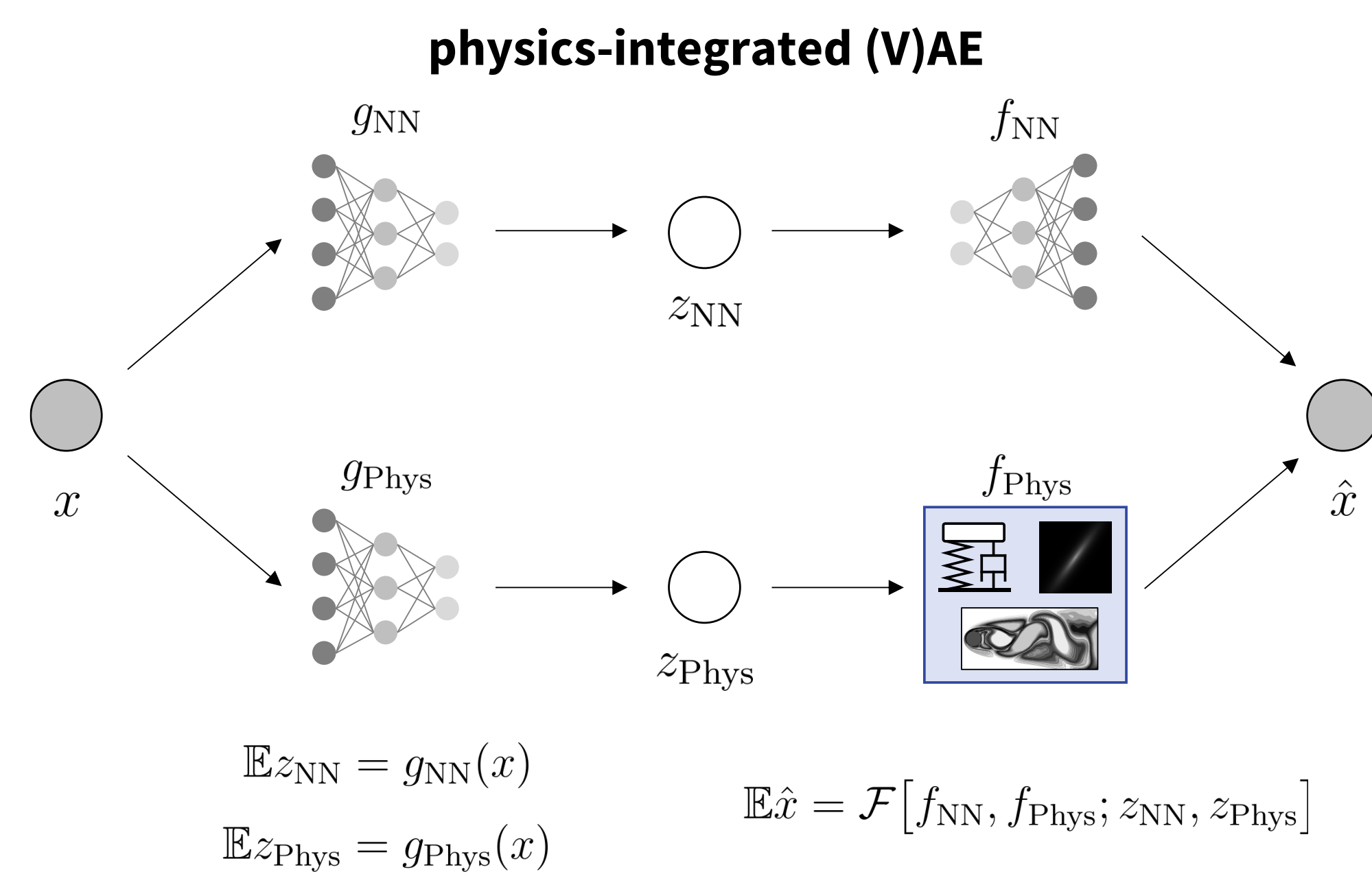
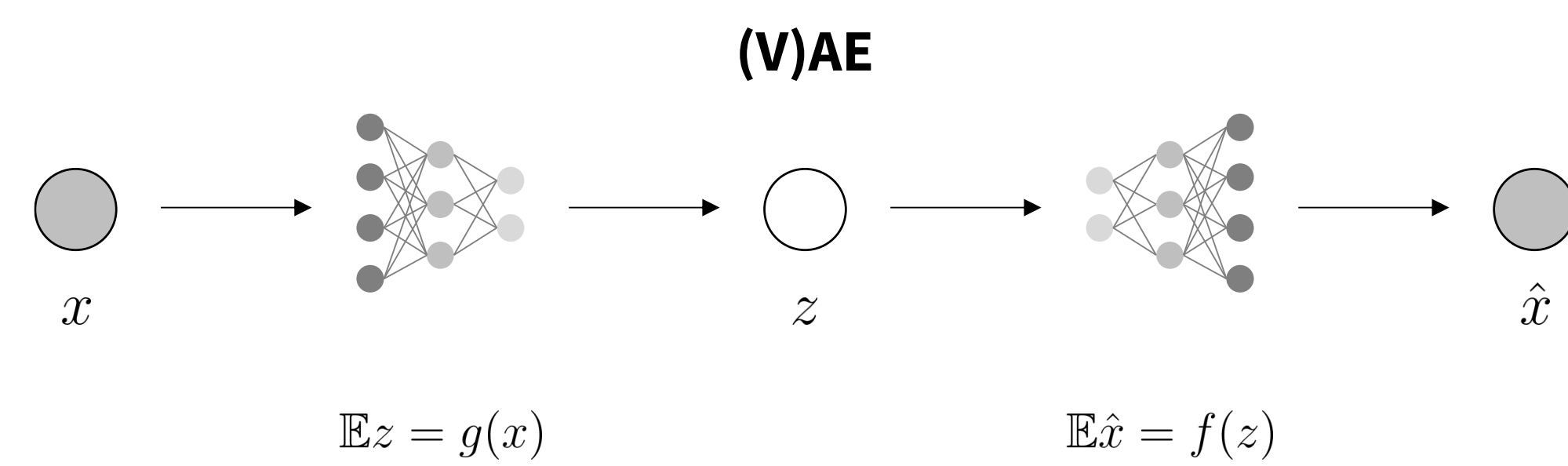
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We address grey-box modeling with deep generative models, particularly VAEs. Technical challenge is to strike a balance between theory-based mathematical (physics) models and data-driven models (i.e., neural nets). We propose a set of regularizers to prevent a physics model from being ignored and to ground the semantics of a part of latent variables by an incomplete physics model.

Deep grey-box modeling needs some regularization

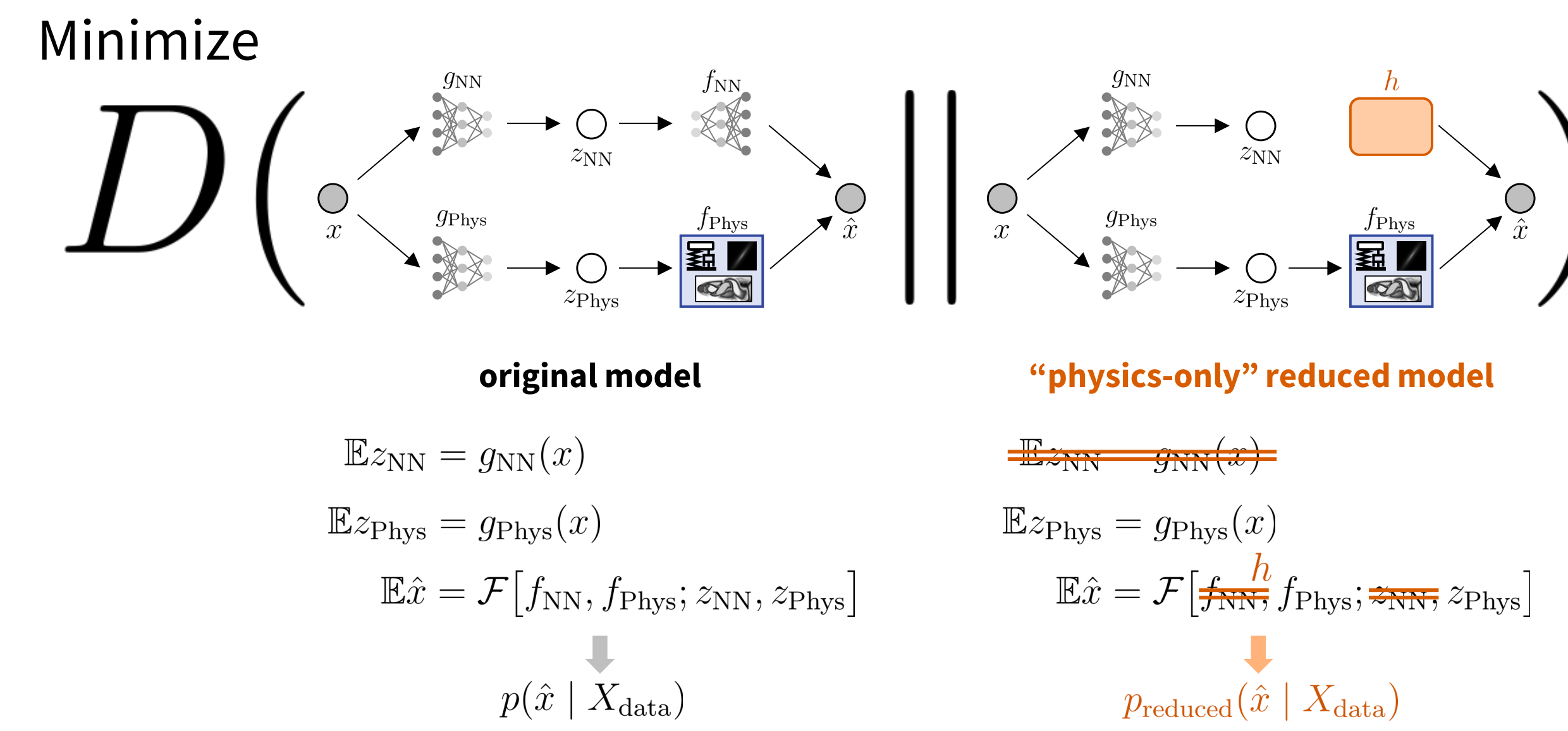


Combining mathematical models based on scientific theories & data-driven models is known as grey-box modeling and can be advantageous in terms of interpretability, extrapolation, and learning efficiency. We consider grey-box modeling with deep neural networks being data-driven part. Particularly, we suppose that VAE's decoder comprises both an incomplete mathematical (physics) model and a neural net (**physics-integrated VAE**).



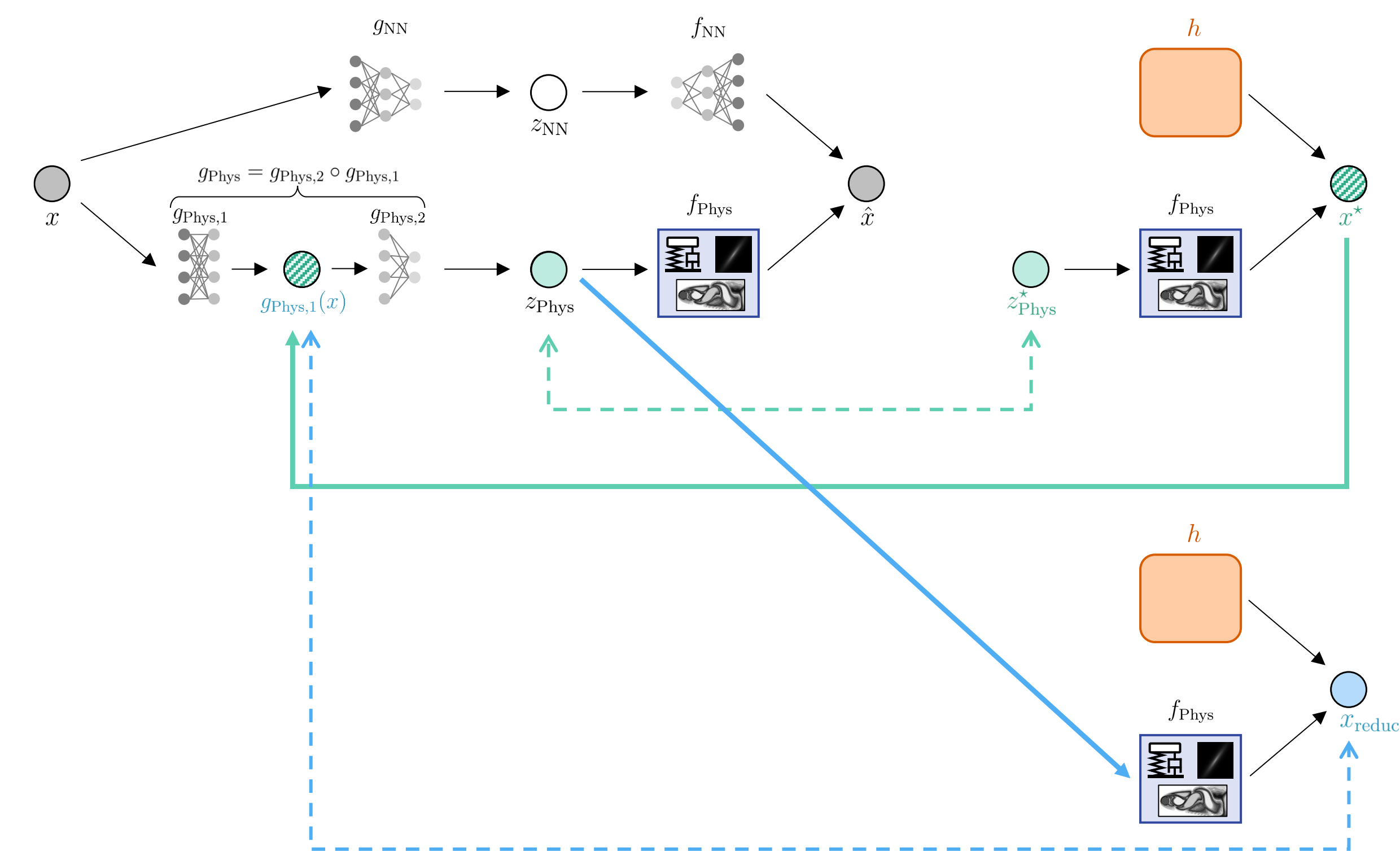
Issue: simply by ERM with -ELBO, physics model can be ignored ☹

Regularization 1: Suppressing excess flexibility of NN



Suppress excess flexibility of neural net f_{NN} by minimizing difference between the full model (left) and a "physics-only" reduced model (right), which is created by replacing f_{NN} with some simple replacement function h (e.g., $h(z) = \text{Id}$, $h(z) = Wz$).

Regularization 2: Data augmentation by physics model



Ground the semantics of z_{Phys} with self-supervision by f_{Phys} . We can generate artificial data x^* from f_{Phys} , but it cannot be put into g_{Phys} directly because f_{Phys} is incomplete, and thus x^* would have different nature from that of real data x .

We try to avoid such difficulty by making the first stage of g_{Phys} output "physics-only" version of x . Let us consider two-stage structure $g_{Phys} = g_{Phys,2} \circ g_{Phys,1}$. We make $g_{Phys,1}(x)$ and $x_{reduced}$ close each other, where $x_{reduced}$ is created by giving z_{Phys} to the physics-only decoder.

Minimize $\mathbb{E}_{data} \|g_{Phys,1}(x) - \text{StopGrad}[x_{reduced}]\|_2^2$ and $\mathbb{E}_{z_{Phys}^*} \|g_{Phys,2}(\text{StopGrad}[x^*]) - z_{Phys}^*\|_2^2$

Experiments

Methods compared:

NN-only	vanilla VAE, decoder only with NN
Phys-only	decoder only with physics model
NN+solver	decoder with NN & corresponding solver (e.g., neural ODEs)
NN+phys	decoder with NN & physics model, but without proposed regularization
NN+phys+reg	proposed method

Pendulum

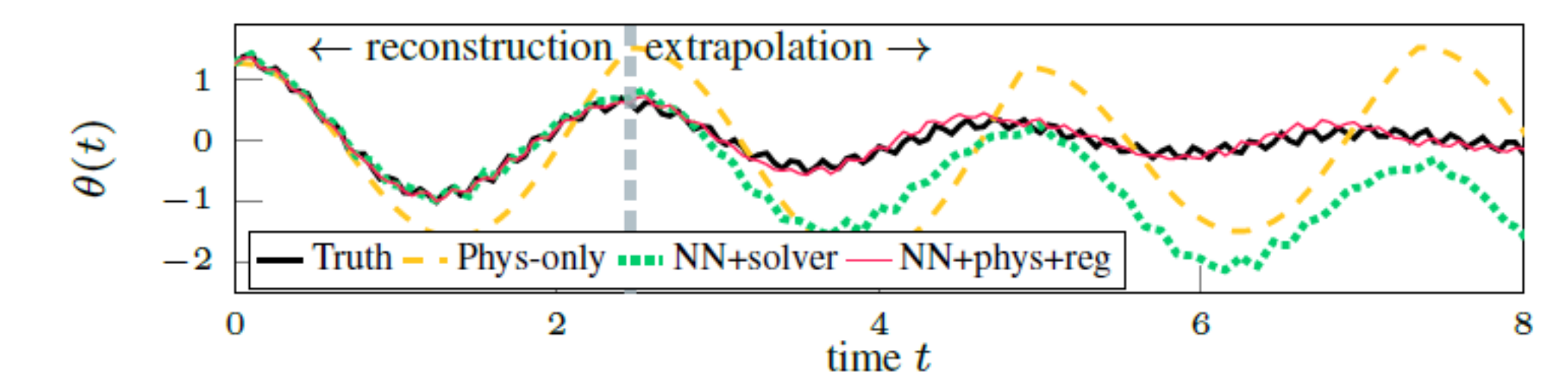
Data generated from: $\ddot{\vartheta} + \omega^2 \sin \vartheta + b\dot{\vartheta} - A\omega^2 \cos(2\pi\phi t) = 0$; 1000 sequences for training.

Model is physics-integrated VAE with decoder:

$$f_{NN,2}(\text{ODESolve}_{\vartheta}[f_{Phys}(\vartheta, z_{Phys}) + f_{NN,1}(\vartheta, z_{NN}) = 0], z_{NN})$$

where $f_{Phys}(\vartheta, z_{Phys}) = \ddot{\vartheta} + z_{Phys}^2 \sin \vartheta$

Result ($0 \leq t < 2.5$ reconstruction, $t \geq 2.5$ extrapolation):



Result (reconstruction / inference errors):

	Pendulum		Advection-diffusion	
	MAE of reconstr.	MAE of inferred ω	MAE of reconstr.	MAE of inferred α
NN-only	0.438 (2.9×10^{-2})	-	0.0396 (2.2×10^{-4})	-
Phys-only	1.55 (7.1×10^{-4})	0.232 (5.9×10^{-3})	0.393 (9.5×10^{-4})	0.0103 (1.5×10^{-3})
NN+solver	0.439 (2.3×10^{-2})	-	0.0388 (1.7×10^{-4})	-
NN+phys	0.370 (4.3×10^{-2})	1.04 (2.2×10^{-1})	0.0404 (1.2×10^{-2})	0.258 (3.2×10^{-1})
NN+phys+reg	0.363 (4.8×10^{-2})	0.229 (3.8×10^{-2})	0.0437 (1.5×10^{-3})	0.00951 (6.2×10^{-2})
Ablations				
$\alpha = 0$	0.396 (4.3×10^{-2})	0.889 (1.9×10^{-1})	0.0461 (1.3×10^{-2})	0.0444 (1.4×10^{-2})
$\beta = 0$	0.372 (4.1×10^{-2})	0.223 (3.6×10^{-2})	0.0747 (2.4×10^{-2})	0.199 (2.3×10^{-1})
$\gamma = 0$	0.381 (4.1×10^{-2})	0.276 (4.2×10^{-2})	0.0588 (9.1×10^{-4})	0.0548 (9.4×10^{-2})

Galaxy images

Data comprise a certain class of galaxy; 400 images for training.

Physics-integrated VAE comprises Gaussian light profile & U-net.

Result (random generation):

